

Ex :- Find a P.I of the equation  
 $(D^2 - D')z = A \cos(lx + my)$   
 where  $A, l, m$  are constants.

Sol<sup>n</sup> :-

$$\begin{aligned}
 \text{P.I} &= \frac{1}{D^2 - D'} A \cos(lx + my) \\
 &= A \cdot \frac{1}{D^2 - D'} \cos(lx + my) \\
 &= A \cdot \frac{1}{-l^2 - D'} \cos(lx + my) \\
 &= -A \left( \frac{1}{D' + l^2} \right) \cos(lx + my) \\
 &= -A \left( \frac{D' - l^2}{D'^2 - l^4} \right) \cos(lx + my) \\
 &= -A \left( \frac{D' - l^2}{-m^2 - l^4} \right) \cos(lx + my) \\
 &= \frac{A}{m^2 + l^4} \left[ -m \sin(lx + my) - l^2 \cos(lx + my) \right] \\
 &= \frac{-A}{m^2 + l^4} \left[ m \sin(lx + my) + l^2 \cos(lx + my) \right]
 \end{aligned}$$

$D^2 = -l^2$   
 $D = -m^2$

5. Equations with variable co-efficients  
 consider equations of the type  
 $Rz + Sz + Tz + f(x, y, z, p, q) = 0 \rightarrow (1)$   
 which may be written in the form

$$L(z) + f(x, y, z, p, q) = 0 \rightarrow (2)$$

where 'L' is the differential operator defined by the equation

$$L = R \frac{\partial^2}{\partial x^2} + S \frac{\partial^2}{\partial x \partial y} + T \frac{\partial^2}{\partial y^2} \rightarrow (3)$$

in which R, S, T are continuous functions of x and y possessing continuous partial derivatives of ~~order~~ as high an order as necessary.

By a suitable change of the independent variables we shall show that any equation of the type (2) can be reduced to one of three canonical forms.

Suppose we change the independent variables from x, y to  $\xi, \eta$  where

$$\xi = \xi(x, y), \quad \eta = \eta(x, y)$$

and we write  $z(x, y)$  as  $z(\xi, \eta)$ , then equation (1) takes the form —

$$A(\xi_x, \xi_y) \frac{\partial^2 z}{\partial \xi^2} + 2B(\xi_x, \xi_y; \eta_x, \eta_y) \frac{\partial^2 z}{\partial \xi \partial \eta}$$

$$+ A(\eta_x, \eta_y) \frac{\partial^2 z}{\partial \eta^2} = F(\xi, \eta, z, \xi_\xi, \xi_\eta) \rightarrow (4)$$

where  $A(u, v) = Ru^2 + Suv + Tv^2 \rightarrow (5)$

and  $B(u_1, v_1; u_2, v_2) = Ru_1u_2 + \frac{1}{2} S(u_1v_2 + u_2v_1) + Tv_1v_2 \rightarrow (6)$

and the function  $F$  is readily derived from the given function  $f$ .

The problem now is to determine  $\xi$  and  $\eta$  so that equation (4) takes the simplest possible form.

Case (a) :  $S^2 - 4RT > 0$

when this condition is satisfied, the roots  $\lambda_1, \lambda_2$  of the equation  $Rx^2 + Sx + T = 0 \rightarrow (7)$  are real and distinct, and the co-efficients of

$\frac{\partial \xi}{\partial x}$  and  $\frac{\partial \xi}{\partial y}$  in equation (4) will vanish if we choose  $\xi$  and  $\eta$  s.t.

$$\frac{\partial \xi}{\partial x} = \lambda_1 \frac{\partial \xi}{\partial y}, \quad \frac{\partial \eta}{\partial x} = \lambda_2 \frac{\partial \eta}{\partial y}$$

A suitable choice would be

$$\xi = f_1(x, y), \quad \eta = f_2(x, y) \rightarrow (8)$$

where  $f_1 = c_1, f_2 = c_2$  are the solutions of the first-order O.D.E

$$\frac{dy}{dx} + \lambda_1(x, y) = 0, \quad \frac{dy}{dx} + \lambda_2(x, y) = 0 \rightarrow (9)$$

respectively.

In general,

$$A(\xi_x, \xi_y) A(\eta_x, \eta_y) - B^2(\xi_x, \xi_y; \eta_x, \eta_y) \\ = (4RT - S^2) (\xi_x \eta_y - \xi_y \eta_x) \quad \rightarrow (10)$$

so that when the A's are zero

$$\tilde{O} = (S^2 - 4RT) (\xi_x \eta_y - \xi_y \eta_x)^2$$

and since  $S^2 - 4RT > 0$ , it follows that

$\tilde{O} > 0$  and therefore that ~~we~~ we may divide

both sides of the equation by it. Hence if we make the substitutions defined by the equations (8) and (9), we find that equation

(1) is reduced to the form

$$\frac{\partial^2 \xi}{\partial \xi \partial \eta} = \phi(\xi, \eta, \xi, \xi_\xi, \xi_\eta) \quad \rightarrow (11)$$

Ans :- Reduce the equation

$$\frac{\partial^2 \xi}{\partial \tilde{x}^2} = \tilde{x}^2 \frac{\partial^2 \xi}{\partial \tilde{y}^2} \text{ to canonical form.}$$

Here  $R = 1, S = 0, T = -\tilde{x}^2$ .

Sol :-

$$S^2 - 4RT = 4\tilde{x}^2$$

$$\frac{d\tilde{y}}{d\tilde{x}} = \frac{S \pm \sqrt{S^2 - 4RT}}{2R} = \pm \frac{2\tilde{x}}{2} = \pm \tilde{x}$$

$$\tilde{y} = \tilde{y} + \frac{\tilde{x}^2}{2}, \quad \tilde{z} = \tilde{y} - \frac{\tilde{x}^2}{2}$$

$$\begin{aligned}
 A(y_x, y_y) &= R y_x^2 + S y_x y_y + T y_y^2 \\
 &= R x^2 + S \cdot x \cdot T + T \\
 &= x^2 - x^2 = 0
 \end{aligned}$$

$$\begin{aligned}
 A(y_x, y_y) &= R y_x^2 + S y_x y_y + T y_y^2 \\
 &= R x^2 - S x + T \\
 &= x^2 - x^2 = 0
 \end{aligned}$$

$$\begin{aligned}
 B(y_x, y_y; n_x, n_y) &= R y_x n_x + \frac{S}{2} (y_x n_y + y_y n_x) + T y_y n_y \\
 &= -x^2 - x^2 = -2x^2
 \end{aligned}$$

$$\frac{\partial z}{\partial x} = \frac{\partial z}{\partial y} \frac{\partial y}{\partial x} + \frac{\partial z}{\partial \eta} \frac{\partial \eta}{\partial x}$$

$$= \frac{\partial z}{\partial y} \cdot x + \frac{\partial z}{\partial \eta} \cdot (-x)$$

$$\frac{\partial z}{\partial y} = \frac{\partial z}{\partial y} \frac{\partial y}{\partial y} + \frac{\partial z}{\partial \eta} \frac{\partial \eta}{\partial y}$$

$$= \frac{\partial z}{\partial y} + \frac{\partial z}{\partial \eta}$$

$$\begin{aligned} \partial_{xx} z &= \partial_{yy} z \tilde{y}_{xx} + 2 \partial_{y\eta} z \tilde{y}_{x\eta} + \partial_{\eta\eta} z \tilde{\eta}_{xx} \\ &= \partial_{yy} z \tilde{y}_{xx} + \partial_{y\eta} z \tilde{y}_{xx} + \partial_{\eta\eta} z \tilde{\eta}_{xx} \end{aligned}$$

$$= \partial_{yy} z \tilde{x} + 2 \partial_{y\eta} z (-\tilde{x}) + \partial_{\eta\eta} z \tilde{x} + \partial_{y\eta} z - \partial_{\eta\eta} z$$

$$\begin{aligned} \partial_{yy} z &= \partial_{yy} z \tilde{y}_{yy} + 2 \partial_{y\eta} z \tilde{y}_{y\eta} + \partial_{\eta\eta} z \tilde{\eta}_{yy} \\ &\quad + \partial_{yy} z \tilde{y}_{yy} + \partial_{\eta\eta} z \tilde{\eta}_{yy} \end{aligned}$$

$$= \partial_{yy} z + 2 \partial_{y\eta} z + \partial_{\eta\eta} z$$

$$\frac{\partial^2 z}{\partial x^2} = \tilde{x} \frac{\partial^2 z}{\partial y^2}$$

$$\begin{aligned} \Rightarrow \partial_{yy} z / \tilde{x} - 2 \partial_{y\eta} z + \partial_{\eta\eta} z \tilde{x} + \partial_{y\eta} z - \partial_{\eta\eta} z \\ = \tilde{x} \partial_{yy} z + 2 \partial_{y\eta} z + \partial_{\eta\eta} z \end{aligned}$$

$$\tilde{x} = y - \eta$$

$$\Rightarrow 4 \tilde{x} \partial_{y\eta} z = \partial_{y\eta} z - \partial_{\eta\eta} z$$

$$\Rightarrow \frac{\partial^2 z}{\partial y \partial \eta} = \frac{1}{4(y-\eta)} (\partial_{y\eta} z - \partial_{\eta\eta} z)$$

Finally, we replace  $z$  by  $y$ .

Case (b) :  $S^2 - 4RT = 0$ . In such circumstances, the roots of equation (7) are equal. We define the function  $\xi$  precisely as in case (a) and take ' $\eta$ ' to be any function of  $x, y$  which is independent of  $\xi$ .

We then have,  $A(\xi_x, \xi_y) = 0$  and hence from equation (10),  $B(\xi_x, \xi_y; \eta_x, \eta_y) = 0$ .

on the other hand,  $A(\eta_x, \eta_y) \neq 0$ ; otherwise  $\eta$  would be a function of  $\xi$ .

Putting  $A(\xi_x, \xi_y)$  and  $B$  equal to zero and dividing by  $A(\eta_x, \eta_y)$ , the canonical form of equation (1) is, in this case,

$$\frac{\partial^2 \zeta}{\partial \eta^2} = \varphi(\zeta, \eta, \xi, \xi_x, \xi_y, \eta_x) \rightarrow (12).$$

Ans :- Reduce the equation

$$\frac{\partial^2 \zeta}{\partial x^2} + 2 \frac{\partial^2 \zeta}{\partial x \partial y} + \frac{\partial^2 \zeta}{\partial y^2} = 0$$

to canonical form and hence solve it.

Sol<sup>n</sup> :-  $R = 1, S = 2, T = 1$ .

$$\alpha^2 + 2\alpha + 1 = 0.$$

$$\frac{dy}{dx} = \frac{S \pm \sqrt{S^2 - 4RT}}{2R} = \frac{2}{2} = 1$$

$$\Rightarrow dx = dy \Rightarrow x - y = c_1$$

$$\frac{B \pm \sqrt{A^2 - 4R^2}}{2R} = \frac{2 \pm \sqrt{4 - 4}}{2} = 1$$

$$\xi = x - y, \quad \eta = x + y.$$

$$A(\xi_x, \xi_y) = R \xi_x^2 + S \xi_x \xi_y + T \xi_y^2 \\ = 1 + 2(-1) + 1 \cdot (+1) = 0$$

$$A(\eta_x, \eta_y) = R \eta_x^2 + S \eta_x \eta_y + T \eta_y^2 \\ = 1 + 2 + 1 = 4$$

$$B(\xi_x, \xi_y; \eta_x, \eta_y) = R \xi_x \eta_x + \frac{S}{2} (\xi_x \eta_y + \xi_y \eta_x) + T \xi_y \eta_y$$

$$= 1 + 1(1-1) + 1 \cdot (-1) = 0$$

$$\frac{\partial^2 \xi}{\partial \eta^2} = 0$$

Thus, the solution of the above equation is

$$\xi = \eta \int_1(\xi) + \int_2(\xi), \text{ where the functions } \int_1 \text{ and } \int_2 \text{ are arbitrary. Hence the original equation has solution } \\ \xi = (x+y) \int_1(x-y) + \int_2(x-y).$$

case (c):  $S^2 - 4RT < 0$ . This is formally the same as case (b) except that now the roots of equations (7) are complex. If we go through the procedure outlined in case (a), we find that the equation (1) reduces to -14 from (11) but that the variables  $\xi, \eta$  are

not real but are in fact complex conjugates.  
 To get a real canonical form, we make the  
 further transformation

$$\alpha = \frac{1}{2}(y + \eta), \quad \beta = \frac{i}{2}(\eta - y)$$

$$\text{Thus, } \frac{\partial^2 \mathcal{L}}{\partial y \partial \eta} = \frac{1}{4} \left( \frac{\partial^2 \mathcal{L}}{\partial x^2} + \frac{\partial^2 \mathcal{L}}{\partial p^2} \right)$$

The desired canonical form is —

$$\frac{\partial^2 \mathcal{L}}{\partial x^2} + \frac{\partial^2 \mathcal{L}}{\partial p^2} = \psi(\alpha, \beta, y, y_\alpha, y_\beta)$$

Ans :- Reduce the equation

$$\frac{\partial^2 z}{\partial x^2} + x \frac{\partial^2 z}{\partial y^2} = 0$$

$$\frac{\Delta E \sqrt{D^2 - 4AC}}{2A}$$

to canonical form

Sol<sup>n</sup> -  $R = 1, S = 0, T = x^2$

$$\frac{dy}{dx} = \frac{\pm \sqrt{-4x^2}}{2} = \pm ix$$

$$y_\beta = iy + \frac{x^2}{2}, \quad \eta = -iy + \frac{x^2}{2}$$

$$\alpha = \frac{1}{2}(y + \eta) = \frac{x^2}{2}$$

$$\beta = \frac{i}{2}(\eta - y) = \frac{i}{2}(-2iy) = y$$

$$A(x_x, x_y) = R x_x^2 + S x_x x_y + T x_y^2$$

$$= x^2$$

$$A(\beta_x, \beta_y) = R \tilde{\beta}_x + S \beta_x \beta_y + T \tilde{\beta}_y$$

$$= x^2$$

$$B(x_x, x_y; \beta_x, \beta_y) = R x_x \beta_x + \frac{1}{2} S (x_x \beta_y + x_y \beta_x) + T x_y \beta_y = 0$$

$$\frac{\partial z}{\partial x} = \frac{\partial z}{\partial \alpha} \cdot \frac{\partial \alpha}{\partial x} + \frac{\partial z}{\partial \beta} \cdot \frac{\partial \beta}{\partial x}$$

$$= \frac{\partial z}{\partial \alpha} \cdot x$$

$$\frac{\partial z}{\partial y} = \frac{\partial z}{\partial \alpha} \cdot \frac{\partial \alpha}{\partial y} + \frac{\partial z}{\partial \beta} \cdot \frac{\partial \beta}{\partial y} = \frac{\partial z}{\partial \beta}$$

$$z_{xx} = z_{\alpha\alpha} \tilde{x}_x + 2 z_{\alpha\beta} x_x \beta_x + z_{\beta\beta} \tilde{\beta}_x + z_{\alpha} x_{xx} + z_{\beta} \beta_{xx}$$

$$= z_{\alpha\alpha} \cdot x^2 + z_{\alpha} \cdot 1$$

$$z_{yy} = z_{\alpha\alpha} \tilde{x}_y + 2 z_{\alpha\beta} x_y \beta_y + z_{\beta\beta} \tilde{\beta}_y + z_{\alpha} x_{yy} + z_{\beta} \beta_{yy}$$

$$= z_{\beta\beta}$$

$$\left[ \begin{array}{l} \alpha = \frac{x^2}{2} \\ \beta = \frac{x^2}{2} \end{array} \right]$$

Thus, the given equation becomes —

$$x^{\sim} \frac{\partial^2 z}{\partial x^2} + \beta x + x^{\sim} \beta \frac{\partial z}{\partial \beta} = 0$$

$$\Rightarrow x^{\sim} \left( \frac{\partial^2 z}{\partial x^2} + \frac{\partial^2 z}{\partial \beta^2} \right) = - \dots \frac{\partial z}{\partial x}$$

$$\Rightarrow \frac{\partial^2 z}{\partial x^2} + \frac{\partial^2 z}{\partial \beta^2} = - \frac{1}{2x} \frac{\partial z}{\partial x}$$

Finally, we replace  $\beta$  by  $y$ .

$$\frac{\partial^2 y}{\partial x^2} + \frac{\partial^2 y}{\partial \beta^2} = - \frac{1}{2x} \frac{\partial y}{\partial x}$$